Case 1. Ulterra motor does not turn on when the Power button on the control panel is pressed and released. The green “System Ready” and red “Status” LEDs do not light up.

Cause: Inadequate voltage, reversed polarity, or the switch/LED circuit board has come loose from the backside of the control panel.

Corrective Action: Verify that the correct voltage is being supplied to the Ulterra motor (24-volts for Ulterra 80 and 36-volts for Ulterra 112) and that polarity has not been inadvertently reversed. If no problems are found with the voltage and power delivery/wiring system, then the Power switch/LED circuit board may have come loose from the control panel during shipment.

To check for this remove the ¼-20 x ½” Phillips head screws that hold the motor side plates in place (two screws each in the left and right side plates). With the side plates removed loosen the two small 10-32 x 3/8” Phillips head screws that hold the control panel cover in place. Lift up the cover as much as possible (due to the motor being stowed there is not much room for this) and look along the backside inner surface of the control panel cover to see if the Power switch/LED display is in place.

If it has come loose, connect the motor to the appropriate voltage. The power can be switched ON by reaching in with a small object (a blade screwdriver, for example) and pressing down on the actuator of the Power switch. The green and red LEDs should light up and the Ulterra can then be deployed via the corded foot pedal or the remote in the normal manner. (Note: if deploying the motor on the boat or benchtop the deploy sequence can be stopped by pressing the Stow/Deploy button.) With the motor deployed (or partially deployed), the control panel cover assembly can be lifted up to expose the main control board assembly. Note the switch/LED circuit board is attached to the main control board by means of the ribbon lead. This switch/LED board snaps into place on the inside surface of the control panel cover.

When re-installing the switch align the actuator pin with the openings in the cover and push the board into position with the two catches, one on each side of the board, engage and hold the board in place. Reinstall the control panel cover and side plates to complete the repair. Test the Power switch ON/OFF function several times to insure proper switch retention. (Note: to turn the motor off with the Power switch hold the switch button down for three seconds, the green and red LEDs should go out when this is done. Release the Power Button, wait about 3 seconds, and press and release the Power button. The green and red LEDs should come back on.) Test stow/deploy of the motor as you are able to on the boat or bench to confirm proper functionality.

Case 2. Ulterra motor green “System Ready” and red “Status” LEDs come on when the Power button is pressed but immediately go off when the Power button is released.

Cause: Inadequate voltage is being supplied to the Ulterra motor. The Ulterra 80 is designed to operate on 24-volts, the Ulterra 112 is designed to operate on 36-volts. With low voltage the Ulterra motors will not stay on when the Power button is pressed and released or, if the green and red LEDs do stay on, they will go out when the command is sent to deploy or stow the motor.
Corrective Action: The only option when this occurs is to provide adequate voltage to the motor. Check batteries for individual voltage values as well as the combined voltage across all the batteries in the series connected battery system. Then check the voltage at the motor battery positive (B+) and battery negative (B-) wires directly at the Ulterra motor to check for a voltage drop. Correct any wiring issues and/or recharge batteries, as required.

Case 3. Ulterra motor will not deploy when the Stow/Deploy button on the foot pedal or the i-Pilot remote is pressed.

A. If no error tone is noted when sending the deploy command:

Possible Cause 1: The Ulterra owner/operator may not be pressing the Stow/Deploy button on the remote twice in quick succession, or if using the corded foot pedal, may not have the pedal in the Ulterra mode and/or may not pressing the Stow/Deploy button on the foot pedal twice in quick succession.

Corrective Action: This is not a problem with the motor. It is designed to require two quick presses of the Stow/Deploy button to avoid accidental deployment of the motor. The only corrective action required is to advise the customer that two button presses in quick succession are required to deploy the motor when using the i-Pilot remote or the corded foot pedal (foot pedal must be in “Ulterra” mode).

Possible Cause 2: This malfunction is often found to be a result of unintentional/accidental damage to one or more of the three wires that connect each of the three Hall Effect Ulterra motor sensors to the main control board. The red, blue, and black wires going to each sensor are enclosed in black or gray mesh tubing running along both sides of the motor base extrusion. These wires can be accidentally damaged, pinched, or cut if care is not used to make certain that the motor (or Quick Release Plate)
mounting bolts do not damage the wires when the bolts are tightened. The cutting of any of the sensor wires will cause the motor to be inoperative.

**Figure 1:** Actual photo supplied by a service provider.

**Corrective Action:** Contact your local Minn Kota service provider for an evaluation.

https://www.minnkotamotors.com/support/service-providers/locate

B. If an error tone is noted when sending the deploy command (this indicates a current limit issue):

**Cause:** The audible error tone when attempting to deploy the motor is an indication that something is restricting or preventing movement of the motor unit and shaft.

**Corrective Action:** To verify that the deploy issue is caused by something that is restricting or binding the motor shaft, we suggest removing the right, front motor ramp.

If the motor does not deploy properly with the ramp removed: Contact your local authorized Minn Kota service provider. https://www.minnkotamotors.com/support/service-providers/locate

If the motor deploys properly with the ramp removed this confirms the binding issue. The next step is to identify the cause. Possible causes include:

- Low or inadequate voltage to the motor/trim housing. Verify that the wiring, connections, plug connections, and battery series connections are all clean and secure. Test the voltage at battery leadwires to ensure correct/adequate voltage is being supplied to the motor.

- A foreign object may be pinched between the steering housing and the aluminum mounting base extrusion (see picture below). Also, check to make certain that the power cable to the steering housing is not getting pinched between the housing and base.
• Dirt or other contaminants may be built up on the composite shaft causing the shaft to stick or bind rather than slide smoothly through the steering housing. To correct this, thoroughly clean and wipe down the shaft with a silicone-rich, water-based spray such as Armor All® or similar product. (Note: you may need to assist the motor deploy sequence by pushing out on the head of the motor while sending a deploy command prior to cleaning.)

• Verify the damper is installed correctly (leg down/toward the control board) and provides resistance to movement (you will need to remove to test this).

• Inspect the tilt nut bracket under the right side plate, verify that it is not bent and that the tilt nut does not show signs of damage.

• Watch the tilt motor when it is running, look for any wobble in the screw shaft as an indication it is bent.

Case 4. Motor is deployed with the motor lower unit less than 14-15 inches below the aluminum base extrusion, it will not steer in either direction and the motor lower unit will not run.

Cause: Motor is in the “prop lockout region”. This feature is used to eliminate the chance of the motor lower unit or prop contact the boat hull.

Corrective Action: Trim the motor down to move the motor lower unit out of the lockout region.

Case 5. Ulterra motor does not properly position the motor lower unit in the “park” position when stowing. (Motor lower unit is not turned to orient it at 90 degrees relative to the motor mounting base so that it lays horizontally when the Ulterra motor pulls the motor on to the motor ramps.)

Cause: The Ulterra motor has been deployed, power switched OFF or disconnected, and the motor lower unit manually turned by hand, or rotated as a result of hitting an obstruction. When this occurs the Ulterra motor’s “park” position is lost and the motor lower unit will no longer be oriented properly when stowing.

Corrective Action: To correct this issue the Ulterra motor must be deployed in the usual manner (two quick button presses of the Stow/Deploy button on the i-Pilot remote, one press of the deploy soft key
button on the i-Pilot Link remote, or two quick button presses of the Stow/Deploy button on the corded foot pedal with the foot pedal in the Ulterra mode.) (Note: if motor was stowed with the prop pointing up or down, you may need to depress the button on the left front motor ramp to deploy the motor. Release that button when the motor starts to deploy.) Send a command to stow the motor via the remote or corded foot pedal. Allow the Ulterra motor to steer the lower unit, raise straight up, rotate the shaft and motor assembly into the horizontal/stow position, then you must STOP the stow sequence by pressing the Stow/Deploy button before the Ulterra starts to pull the lower unit on to the motor ramps. At this point, turn the Ulterra OFF by pressing and holding the Power button on the control panel about three seconds until the green System Ready LED turns off. Wait about five seconds, then manually rotate the motor lower unit into the “park” position by grasping and turning either the lower unit or the control box head. The motor should be positioned so that it is laying horizontally at 90 degrees to the mounting base with the prop to the left or right (per your preference). Turn the power back on at the control panel and stow/deploy the motor to test and confirm that the “park” position has been reset correctly. Repeat this procedure, if necessary, to tweak the “park” position. This completes the procedure for resetting the “park position”.

Case 6. The Ulterra motor does not rotate into the horizontal position when stowing, or the vertical position when deploying, at the appropriate time. During the stow sequence the motor lower unit should come straight up and begin to rotate into the horizontal position when the lower unit is about twelve (12) to thirteen (13) inches below the aluminum base extrusion. During the deploy sequence the motor lower unit should extend about five (5) to six (6) inches out from the steering housing and then begin to rotate into the vertical position.

Cause: The trim module has lost its position count and needs to be reset.

Corrective Action: The Reset Procedure must be performed. (Also see Trim/Stow Reset Procedure) To do this the motor MUST be in the deployed position, with the motor and shaft assembly vertical and the latch pin in the steering housing engaged into the aluminum base extrusion catches. Then, with the voltage appropriate for the motor being serviced supplied to the motor, press and release the Power button. The green system ready LED should be displayed, wait three (3) seconds then press and release the Power button three (3) times in quick succession within a two (2) second time period. The motor lower unit and shaft assembly should then come straight up until the motor belt collar contacts the underside of the steering housing, pause, and then extend back out about six (6) inches from the steering housing. This resets the trim module counter and completes this procedure.